Response set imbalance and non-response bias: a theoretical study with full use of auxiliary information

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The crucial question: Will better balanced response guarantee better accuracy (lower variance and/or bias) in the estimates?

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and a design weight $d_{k}=1 / \pi_{k}$.

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We assume that the auxiliary vector can be constructed as such that

$$
\boldsymbol{\mu}^{\prime} \mathbf{x}_{k}=1, \forall k \in s, \text { for some vector } \boldsymbol{\mu} \text { independent on } k .
$$

## Balance and imbalance

The response set is balanced if

$$
\overline{\mathbf{x}}_{r}=\frac{\sum_{r} d_{k} \mathbf{x}_{k}}{\sum_{r} d_{k}}=\frac{\sum_{s} d_{k} \mathbf{x}_{k}}{\sum_{s} d_{k}}=\overline{\mathbf{x}}_{s} .
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We measure imbalance with

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I M B=P^{2}\left(\overline{\mathbf{x}}_{r}-\overline{\mathbf{x}}_{s}\right)^{\prime} \Sigma_{s}^{-1}\left(\overline{\mathbf{x}}_{r}-\overline{\mathbf{x}}_{s}\right),
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P=\sum_{r} d_{k} / \sum_{s} d_{k}, \quad \Sigma_{s}=\sum_{s} d_{k} \mathbf{x}_{k} \mathbf{x}_{k}^{\prime} / \sum_{s} d_{k} .
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$I M B$ takes values between $0 \leq I M B \leq P(1-P)$.

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Guiding data collection with $I M B$ - monitoring response.

## Estimation based on $s$

Horvitz-Thompson estimator (HT):

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\hat{Y}_{F U L}=\sum_{s} d_{k} y_{k}=\hat{N} \bar{y}_{s} .
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\hat{Y}_{C A L}^{*}=\sum_{s} d_{k} w_{k} y_{k},
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Weights $w_{k}$ satisfy calibration requirements:

$$
\sum_{s} d_{k} w_{k} \mathbf{x}_{k}^{\prime}=\sum_{U} \mathbf{x}_{k}^{\prime}
$$

## Estimation under non-response

## The expansion estimator:

$$
\hat{Y}_{E X P}=\hat{N} \sum_{r} d_{k} y_{k} / \sum_{r} d_{k}=\hat{N} \bar{y}_{r},
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where $\bar{y}_{r}=\sum_{r} d_{k} y_{k} / \sum_{r} d_{k}$.

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The calibration estimator under non-response:

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\hat{Y}_{C A L}=\sum_{r} d_{k} g_{k} y_{k},
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g_{k}=\left(\sum_{s} d_{k} \mathbf{x}_{k}\right)^{\prime}\left(\sum_{r} d_{k} \mathbf{x}_{k} \mathbf{x}_{k}^{\prime}\right)^{-1} \mathbf{x}_{k}
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## Imbalance of study variable

The study variable imbalance is characterised by

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\bar{y}_{r}-\bar{y}_{s},
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If we multiple with $\hat{N}$ we get:

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\hat{N}\left(\bar{y}_{r}-\bar{y}_{s}\right)=\hat{Y}_{E X P}-\hat{Y}_{F U L} .
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Let us expand the right side by $\pm \hat{Y}_{C A L}$ :

$$
\hat{N}\left(\bar{y}_{r}-\bar{y}_{s}\right)=\left(\hat{Y}_{E X P}-\hat{Y}_{C A L}\right)+\left(\hat{Y}_{C A L}-\hat{Y}_{F U L}\right)
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## Non-response bias

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where $\mathbf{b}_{r}=\left(\sum_{r} d_{k} \mathbf{x}_{k} \mathbf{x}_{k}^{\prime}\right)^{-1} \sum_{r} d_{k} \mathbf{x}_{k} y_{k}$ and $\mathbf{b}_{s}=\left(\sum_{s} d_{k} \mathbf{x}_{k} \mathbf{x}_{k}^{\prime}\right)^{-1} \sum_{s} d_{k} \mathbf{x}_{k} y_{k}$.

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This decompositions highlights two undesirable differences:

- Difference due to imbalance in the response
- Difference due to biased regression


## Previous results

Let's denote

$$
\Delta_{r}=\left(\mathbf{b}_{r}-\mathbf{b}_{s}\right)^{\prime} \overline{\mathbf{x}}_{s}=\left(\hat{Y}_{C A L}-\hat{Y}_{F U L}\right) / \hat{N}
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and investigate the effect of imbalance on $\Delta_{r}$.

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Särndal et. al (2016) showed that under certain simplifying conditions, the conditional mean $E\left(\Delta_{r} \mid \overline{\mathbf{x}}_{r}, m, s\right)=0$ and the conditional variance

$$
V\left(\Delta_{r} \mid \overline{\mathbf{x}}_{r}, m, s\right) \approx \frac{S_{y}^{2}}{m}\left(1-p+\frac{I M B}{p^{2}}\right)
$$

where $m$ is the number of respondents, $p=m / n$ is the response rate, $S_{y}^{2}=\sum_{j=1}^{J} n_{j} / n S_{y j}^{2}$ and $S_{y j}^{2}=\sum_{s_{j}}\left(y_{k}-\bar{y}_{s_{j}}\right)^{2} /\left(n_{j}-1\right), j=1, \ldots, J$.

## Further exploration

For simplification let us redefine the calibration estimator under non-response:

$$
\hat{Y}_{C A L 2}=\sum_{r} d_{k} g_{U k} y_{k}
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where $g_{U k}=\left(\sum_{U} \mathbf{x}_{k}\right)^{\prime}\left(\sum_{r} d_{k} \mathbf{x}_{k} \mathbf{x}_{k}^{\prime}\right)^{-1} \mathbf{x}_{k}$.

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Let us expand the $\left(\bar{y}_{r}-\bar{y}_{s}\right)$ decomposition with $\pm \hat{Y}_{C A L}^{*}$ :

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\hat{N}\left(\bar{y}_{r}-\bar{y}_{s}\right)=\left(\hat{Y}_{E X P}-\hat{Y}_{C A L 2}\right)+\left(\hat{Y}_{C A L 2}-\hat{Y}_{C A L}^{*}\right)+\left(\hat{Y}_{C A L}^{*}-\hat{Y}_{F U L}\right)
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where $\overline{\mathbf{x}}_{U}=\sum_{U} \mathbf{x}_{k} / \sum_{s} d_{k}$.

## Further exploration

Let the auxiliary vector be a grouping vector, so that $\mathbf{x}_{k}=(0, \ldots, 1, \ldots, 0)^{\prime}$, where the only 1 indicates the unique group (out of $J$ possible) to which $k$ belongs. Then

$$
\hat{N}\left(\overline{\mathbf{x}}_{r}-\overline{\mathbf{x}}_{U}\right)^{\prime} \mathbf{b}_{r}=\hat{N} \sum_{j=1}^{J} \bar{y}_{r j}\left(\frac{m_{j}}{m}-\frac{N_{j}}{\hat{N}}\right),
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& \hat{N}\left(\overline{\mathbf{x}}_{U}-\overline{\mathbf{x}}_{s}\right)^{\prime} \mathbf{b}_{s}=\hat{N} \sum_{i=1}^{J} \bar{y}_{s j}\left(\frac{N_{j}}{\hat{N}_{-}}-\frac{n_{j}}{n}\right) .
\end{aligned}
$$

## Simulations

A sample of $n=20$ is fixed and all possible response sets are considered where $m=12$. The auxiliary vector is a group vector, $I M B$ and $\left(\mathbf{b}_{r}-\mathbf{b}_{s}\right)^{\prime} \overline{\mathbf{x}}_{U}$ is calculated for 56576 response sets.


## Simulations

Variance of $\left(\mathbf{b}_{r}-\mathbf{b}_{s}\right)^{\prime} \overline{\mathbf{x}}_{U}$ by IMB value.


## References:

- Särndal, C.E., Lumiste, K., and Traat, I. (2016) Reducing the Response Imbalance: Is the Accuracy of the Survey Estimates Improved? Survey Methodology, 42 (2): 219-238.
- Lumiste, K. (2018) Improving accuracy of survey estimators by using auxiliary information in data collection and estimation stages. Dissertation, University of Tartu.

